The multivariate normal distribution

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Introduction

- Today we will introduce the multivariate normal distribution and attempt to discuss its properties in a fairly thorough manner
- The multivariate normal distribution is by far the most important multivariate distribution in statistics
- It's important for all the reasons that the one-dimensional Gaussian distribution is important, but even more so in higher dimensions because many distributions that are useful in one dimension do not easily extend to the multivariate case

Motivation

- In the univariate case, the family of normal distributions can be constructed from the standard normal distribution through the location-scale transformation $\mu + \sigma Z$, where $Z \sim N(0,1)$; the resulting random variable has a $N(\mu,\sigma^2)$ distribution
- A similar approach can be taken with the multivariate normal distribution, although some care needs to be taken with regard to whether the resulting variance is singular or not

Standard normal

- First, the easy case: if Z_1, \ldots, Z_r are mutually independent and each follows a standard normal distribution, the random vector **z** is said to follow an r-variate standard normal distribution, denoted $\mathbf{z} \sim N_r(\mathbf{0}, \mathbf{I}_r)$
- Remark: For multivariate normal distributions and identity matrices, I will usually leave off the subscript from now on when it is either unimportant or able to be figured out from context
- If $\mathbf{z} \sim N_r(\mathbf{0}, \mathbf{I})$, its density is

$$p(\mathbf{z}) = (2\pi)^{-r/2} \exp\{-\frac{1}{2}\mathbf{z}^{\mathsf{T}}\mathbf{z}\}\$$

Multivariate possibilities

- Like the univariate case, we can construct multivariate distributions through linear combinations
- Before we define the multivariate normal distribution, however, note that there is no guarantee that the dimension remains the same in such a transformation:
 - Suppose $z_1, z_2, z_3 \stackrel{\scriptscriptstyle \perp}{\sim} \mathrm{N}(0,1)$
 - The dimension could decrease: $x_1 = z_1 + 2z_3, x_2 = -z_2$
 - Or increase:

$$x_1 = z_1 + 2z_2$$

$$x_2 = z_1 - z_2$$

$$x_3 = z_2 - z_3$$

$$x_4 = z_1 + z_2 + z_3$$

Multivariate normal distribution

- Definition: Let \mathbf{x} be a $d \times 1$ random vector with mean vector $\boldsymbol{\mu}$ and covariance matrix $\boldsymbol{\Sigma}$, where $\mathrm{rank}(\boldsymbol{\Sigma}) = r > 0$. Let $\boldsymbol{\Gamma}$ be a $r \times d$ matrix such that $\boldsymbol{\Sigma} = \boldsymbol{\Gamma}^{\top} \boldsymbol{\Gamma}$. Then \mathbf{x} is said to have a d-variate normal distribution of rank r if its distribution is the same as that of the random vector $\boldsymbol{\mu} + \boldsymbol{\Gamma}^{\top} \mathbf{z}$, where $\mathbf{z} \sim \mathrm{N}_r(\mathbf{0}, \mathbf{I})$.
- ullet This is typically denoted $\mathbf{x} \sim \mathrm{N}_d(oldsymbol{\mu}, oldsymbol{\Sigma})$

Density

• Suppose $\mathbf{x} \sim \mathrm{N}_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ and that $\boldsymbol{\Sigma}$ is full rank; then \mathbf{x} has a density:

$$p(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = (2\pi)^{-d/2} |\boldsymbol{\Sigma}|^{-1/2} \exp\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^{\top} \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\},$$

where $|\Sigma|$ denotes the determinant of Σ

• We will not really concern ourselves with determinants and their properties in this course, although it is worth pointing out that if Σ is singular, then $|\Sigma|=0$ and the above result does not hold (or even make sense)

Singular case

- ullet In fact, if Σ is singular, then ${f x}$ does not even *have* a density
- This is connected to our earlier discussion of the Lebesgue decomposition theorem: if Σ is singular, then the distribution of $\mathbf x$ is singular (not discrete, but also doesn't have a density)
- This is the reason why the MVN must be constructed as we did we can't define the distribution by its density, we must instead say that it has the same distribution as $\mu + \Gamma^{\top} \mathbf{z}$, where \mathbf{z} has a well-defined density

Moment generating function

- For this reason, when working with multivariate normal distributions or showing that some random variable y follows a multivariate normal distribution, it is often easier to work with moment generating functions or characteristic functions, which are well-defined even if Σ is singular
- If $\mathbf{x} \sim \mathrm{N}_d(oldsymbol{\mu}, oldsymbol{\Sigma})$, then its moment generating function is

$$m(\mathbf{t}) = \exp{\{\mathbf{t}^{\mathsf{T}}\boldsymbol{\mu} + \frac{1}{2}\mathbf{t}^{\mathsf{T}}\boldsymbol{\Sigma}\mathbf{t}\}},$$

where $\mathbf{t} \in \mathbb{R}^d$

 We'll come back to its characteristic function in a future lecture

Partitioned matrices

- We will often partition vectors and matrices in this class
- The idea of a partitioned matrix is to think of a large matrix as a collection of smaller submatrices:

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 2 & 7 \\ 1 & 5 & 6 & 2 \\ 3 & 3 & 4 & 5 \\ 3 & 3 & 6 & 7 \end{bmatrix}$$

can be partitioned into four 2×2 blocks

$$\mathbf{A} = \begin{bmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{21} & \mathbf{A}_{22} \end{bmatrix}, \text{ where } \mathbf{A}_{11} = \begin{bmatrix} 1 & 2 \\ 1 & 5 \end{bmatrix}, \, \mathbf{A}_{12} = \begin{bmatrix} 2 & 7 \\ 6 & 2 \end{bmatrix}, \, \dots$$

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Transposing partitioned matrices

• The transpose of a partitioned matrix is

$$\mathbf{A}^{ op} = egin{bmatrix} \mathbf{A}_{11}^{ op} & \mathbf{A}_{21}^{ op} \ \mathbf{A}_{12}^{ op} & \mathbf{A}_{22}^{ op} \end{bmatrix}$$

 Note that if A is symmetric, as in the case of a covariance matrix or matrix of second derivatives, then

$$\mathbf{A}_{12}^{\scriptscriptstyle \top} = \mathbf{A}_{21}$$

"Middle" partitions

- It is easy to visualize a partition when each corner is a block
- However, "middle" partitions are also common; for example

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

could be partitioned so that ${\bf A}_{22}$ is isolated; in that case ${\bf A}_{2,-2}=[4\ 6]$ would be equivalent to ${\bf A}_{12}$ in a "corner" partition

 We'll return to this point later when we discuss conditional distributions

Permutation matrices

- Alternatively, you could think about reordering the matrix prior to partitioning it so that the portion you wish to isolate is in the corner, not the middle
- Formally, this would involve multiplication by a permutation matrix: a square matrix with exactly one entry equal to 1 in each row and each column and all other entries equal to 0
- An important fact to be aware of is that for any permutation matrix ${\bf P}$ and invertible matrix ${\bf A}$

$$(\mathbf{P} \mathbf{A} \mathbf{P}^{\top})^{-1} = \mathbf{P} \mathbf{A}^{-1} \mathbf{P}^{\top}$$

(in other words, the inverse of the reordered matrix is the same as reordering the inverse)

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Why are partitioned matrices important?

- Partitioned matrices are important for many reasons, but one reason they are particularly important in this class is because of nuisance parameters
- In multiparameter problems, we are rarely interested in inference for all parameters simultaneously
- Instead, only a subset are typically of interest, and the remaining parameters are considered "nuisance parameters"

 we then partition the parameter space (and the corresponding information matrices) accordingly

Independence

- Before moving on, let us note that there is a connection between covariance and independence in the multivariate normal distribution
- Theorem: Suppose $\mathbf{x} \sim \mathrm{N}_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$. If $\mathbf{x} = (\mathbf{x}_1; \, \mathbf{x}_2)$ and the corresponding off-diagonal of $\boldsymbol{\Sigma}_{12}$ is zero, then \mathbf{x}_1 and \mathbf{x}_2 are independent.
- In particular, if Σ is a diagonal matrix, then x_1,\ldots,x_n are mutually independent

Independence (caution)

- It is worth pointing out a common mistake here: $\mathrm{Cov}(X_1,X_2)=0 \implies X_1 \perp \!\!\! \perp X_2$ only if X_1 and X_2 are multivariate normal
- For example, suppose $X \sim N(0,1)$ and $Y = \pm X$, each with probability $\frac{1}{2}$
- X and Y are both normally distributed, and $\mathrm{Cov}(X,Y)=0$, but they are clearly not independent

Linear combinations

- A very important property of the multivariate normal distribution is that its linear combinations are also normally distributed
- Theorem: Let b be a $k \times 1$ vector of constants, B a $k \times d$ matrix of constants, and $\mathbf{x} \sim N_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$. Then

$$\mathbf{b} + \mathbf{B}\mathbf{x} \sim N_k(\mathbf{B}\boldsymbol{\mu} + \mathbf{b}, \mathbf{B}\boldsymbol{\Sigma}\mathbf{B}^{\top}).$$

Corollary

- A useful corollary of this result is that we can always "standardize" a variable with an MVN distribution
- Let's consider the full-rank case first (i.e., Σ is nonsingular and positive definite, and so is Σ^{-1})
- Corollary: Let $\mathbf{x} \sim \mathrm{N}_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$. Then

$$\Sigma^{-1/2}(\mathbf{x} - \boldsymbol{\mu}) \sim N_d(\mathbf{0}, \mathbf{I}),$$

where $\Sigma^{-1/2}$ is the square root of Σ^{-1} .

Corollary: Low rank case

- If Σ is singular, then $\Sigma^{-1/2}$ does not exist, although we can still standardize the distribution
- Corollary: Let $\mathbf{x} \sim \mathrm{N}_d(\pmb{\mu}, \pmb{\Sigma})$, where $\pmb{\Sigma}$ is rank r with $\pmb{\Gamma}^{\top} \pmb{\Gamma} = \pmb{\Sigma}$. Then

$$(\mathbf{\Gamma}\mathbf{\Gamma}^{\top})^{-1}\mathbf{\Gamma}(\mathbf{x} - \boldsymbol{\mu}) \sim N_r(\mathbf{0}, \mathbf{I}).$$

Quadratic forms

- In the univariate case, if $Z \sim N(0,1)$, then Z^2 follows a distribution known as the χ^2 distribution
- Furthermore, if Z_1,\ldots,Z_n are mutually independent and each $Z_i \sim \mathrm{N}(0,1)$, then $\sum_i Z_i^2 \sim \chi_n^2$, where χ_n^2 denotes the χ^2 distribution with n degrees of freedom
- Thus, it is a straightforward consequence of our previous corollaries that if $\mathbf{x} \sim \mathrm{N}_d(\mathbf{0}, \boldsymbol{\Sigma})$ and $\boldsymbol{\Sigma}$ is nonsingular,

$$\mathbf{x}^{\top}\mathbf{\Sigma}^{-1}\mathbf{x} \sim \chi_d^2$$

Quadratic forms: low rank

• Similarly, it is always the case that if $\mathbf{x} \sim \mathrm{N}_d(\mathbf{0}, \mathbf{\Sigma})$ with $\mathbf{\Sigma} = \mathbf{\Gamma}^{\scriptscriptstyle \top} \mathbf{\Gamma}$, then

$$\mathbf{x}^{\mathsf{T}} \mathbf{\Sigma}^{-} \mathbf{x} \sim \chi_r^2,$$

where r is the rank of Σ and

$$\mathbf{\Sigma}^- = \mathbf{\Gamma}^{\scriptscriptstyle op} (\mathbf{\Gamma} \mathbf{\Gamma}^{\scriptscriptstyle op})^{-1} (\mathbf{\Gamma} \mathbf{\Gamma}^{\scriptscriptstyle op})^{-1} \mathbf{\Gamma}$$

• As discussed in our review last time, Σ^- is a quantity known as a *generalized inverse*, which you'll learn more about in the linear models course

Non-central chi square distribution

- If $\mu \neq 0$, then the quadratic form follows something called a non-central χ^2 distribution
- If $Z_1,\ldots,Z_n\stackrel{\!\!\!\perp}{\sim} N(\mu_i,1)$, then the distribution of $\sum_i Z_i^2$ is known as the noncentral χ_n^2 distribution with noncentrality parameter $\sum_i \mu_i^2$
- Thus, if $\mathbf{x} \sim \mathrm{N}_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, we have

$$\mathbf{x}^{\mathsf{T}} \mathbf{\Sigma}^{-1} \mathbf{x} \sim \chi_d^2(\boldsymbol{\mu}^{\mathsf{T}} \mathbf{\Sigma}^{-1} \boldsymbol{\mu}),$$

or

$$\mathbf{x}^{\mathsf{T}} \mathbf{\Sigma}^{-} \mathbf{x} \sim \chi_r^2 (\boldsymbol{\mu}^{\mathsf{T}} \mathbf{\Sigma}^{-} \boldsymbol{\mu})$$

if Σ is singular

Marginal distributions

 Finally, let us consider some results related to partitions of the multivariate normal distribution:

$$\mathbf{x} = \left[egin{array}{c} \mathbf{x}_1 \\ \mathbf{x}_2 \end{array}
ight], \quad \boldsymbol{\mu} = \left[egin{array}{c} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{array}
ight], \quad \boldsymbol{\Sigma} = \left[egin{array}{c} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{array}
ight]$$

 Conveniently, the marginal distributions are exactly what you would intuitively think they should be:

$$\mathbf{x}_1 \sim \mathrm{N}(\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_{11})$$

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Conditional

- A more complicated question: what is the distribution of \mathbf{x}_1 given \mathbf{x}_2 ?
- ullet This gets messy if Σ is singular, but if Σ is full rank, then

$$\mathbf{x}_1|\mathbf{x}_2 \sim \mathrm{N}\left(\boldsymbol{\mu}_1 + \boldsymbol{\Sigma}_{12}\boldsymbol{\Sigma}_{22}^{-1}(\mathbf{x}_2 - \boldsymbol{\mu}_2), \boldsymbol{\Sigma}_{11} - \boldsymbol{\Sigma}_{12}\boldsymbol{\Sigma}_{22}^{-1}\boldsymbol{\Sigma}_{21}\right)$$

• As mentioned earlier, note that if $\Sigma_{12}=\mathbf{0}$, then \mathbf{x}_1 and \mathbf{x}_2 are independent and $\mathbf{x}_1|\mathbf{x}_2\sim \mathrm{N}(\pmb{\mu}_1,\pmb{\Sigma}_{11});$

Schur complement

- The quantity $\Sigma_{11} \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}$ is known in linear algebra as the *Schur complement*; it comes up all the time in statistics and we will see it repeatedly in this course
- It is the *inverse* of the (1,1) block of Σ^{-1} ; more explicitly, letting $\Theta = \Sigma^{-1}$,

$$\boldsymbol{\Theta}_{11}^{-1} = \boldsymbol{\Sigma}_{11} - \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} \boldsymbol{\Sigma}_{21}$$

• Conceptually, it represents the reduction in the variability of \mathbf{x}_1 that we achieve by learning \mathbf{x}_2 (or equivalently, the increase in our uncertainty about \mathbf{x}_1 if we don't know \mathbf{x}_2)

Precision matrix

- The inverse of the covariance matrix, $\Theta = \Sigma^{-1}$, is known as the *precision matrix* and is a rather interesting quantity in its own right
- In fact, many statistical procedures are more concerned with estimating Θ than Σ
- One key reason for this is that Θ encodes conditional independence relationships that are often of interest in learning the structure of \mathbf{x} in terms of how variables are related to each other

Conditional independence result

- Suppose we partition x into x₁, containing two variables of interest, and x₂ containing the remaining variables
- Then by the results we've obtained already, if $\mathbf{x} \sim \mathrm{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, then $\mathbf{x}_1 | \mathbf{x}_2$ is multivariate normal with covariance matrix $\boldsymbol{\Theta}_{11}^{-1}$
- ullet Thus, if any off-diagonal element of ullet is zero, then the corresponding variables are conditionally independent given the remaining variables
- This is of interest in many statistical problems

Example: $X \to Y \to Z$

```
# Conditional independence and the precision matrix
n < -100000
x \leftarrow rnorm(n)
y \leftarrow x + rnorm(n)
z \leftarrow y + rnorm(n)
cbind(x, y, z) > cor()
#
            X
# x 1.0000000 0.7061447 0.5762403
# y 0.7061447 1.0000000 0.8160535
# z 0.5762403 0.8160535 1.0000000
cbind(x, y, z) > cor() > solve()
# x 1.994576e+00 -1.408516 6.940939e-05
# y -1.408516e+00 3.988160 -2.442908e+00
 z 6.940939e-05 -2.442908 2.993504e+00
```

Application

- One application of this idea is in learning gene regulatory networks
- Suppose the expression levels of various genes follow a multivariate normal distribution (at least approximately)
- Learning which elements of Θ are nonzero corresponds to learning which pairs of genes have a direct relationship with one another, as opposed to being merely correlated through the effects of other genes that affect them both